

## ANS KEY

1. In Parts **a** and **b** determine the form of a particular solution  $y_p = y_p(t)$  having the **least** number of unknown constants. **DO NOT DETERMINE** the unknown constants appearing in your answers in Parts **a** and **b**.

**a. 2pt**  $y'' - 14y' + 49y = 2t^2e^{7t}$

**ANS.**  $t^2(At^2 + Bt + C)e^{7t}$

7 is a double root of the characteristic polynomial.

Take off 1pt more missing factor of  $t^2$ .

Take off 2pts for any other error.

**b. 2pt**  $y'' - 50y' + 49y = 3te^t$

**ANS.**  $t(At + B)e^t$

1 is a simple root of the characteristic polynomial.

Take off 1pt more missing factor of  $t$ .

Take off 2pts for any other error.

- c. 7pt** Without using Laplace transforms, find a particular solution to the following ODE:

$$y'' + 3y = e^t \sin 2t$$

(In this part you need to **determine the unknown constant(s) in the solution.**

**ANS.** Solve the complexified equation and then take imaginary part

$$y'' + 3y = e^{(1+2i)t}$$

Plug in  $y_C = Ae^{(1+2i)t}$  since  $1 + 2i$  is not a root of the characteristic polynomial. (2pts)

$$y'_C = A(1 + 2i)e^{(1+2i)t} \text{ and } y'_C = A(-3 + 4i)e^{(1+2i)t}. \text{ (1pt)}$$

$$\text{Therefore, } L[y_C] = A(3 + (-3 + 4i))e^{(1+2i)t}. \text{ (2pt)}$$

We conclude that  $A = 1/(4i) = -i/4$  and hence the imaginary part of  $y_C$  is  $y_p = (-1/4) \cos(2t)$  (2pt)

**Alternatively,**

$$\text{plug in } y_p = e^t(A \cos(2t) + B \sin(2t)). \text{ (2pt)}$$

$$\text{Taking the derivative: } y'_p = e^t((A + 2B) \cos(2t) + (B - 2A) \sin(2t)). \text{ (1pt)}$$

$$\text{and again: } y''_p = e^t((-3A + 4B) \cos(2t) + (-3B - 4A) \sin(2t)). \text{ (2pt)}$$

$$\text{Therefore, } L[y_p] = e^t(4B \cos(2t) - 4A \sin(2t)). \text{ (1pt)}$$

$$\text{We conclude that } 4B = 0 \text{ and } -4A = 1, \text{ ie, } y_p = (-1/4) \cos(2t). \text{ (1pt)}$$

2. Assume that acceleration due to gravity  $g$  is equal to 10 meter/sec<sup>2</sup>. An object with mass 2 kg stretches a spring 2.5 meters to the equilibrium position. Assume that there is no damping device attached and also assume that at time  $t = 0$  the object is released 1 meter below its equilibrium position with a upward velocity of 4 meter/sec.

a. **3pt** Write down a differential equation with initial conditions for  $y(t)$  for the displacement of the object below its equilibrium position.

**ANS.**  $mg = kL$  Therefore  $k = 8$  (1pt)

$$2y'' + 8y = 0 \text{ (1pt)}$$

$$y(0) = 1 \quad y'(0) = -4 \text{ (1pt)}$$

b. **4pt** Find a formula for  $y(t)$

**ANS.**  $y = c_1 \cos 2t + c_2 \sin 2t$  (2pt)

$$y' = -2c_1 \sin 2t + 2c_2 \cos 2t \text{ (1pt)}$$

$$c_1 = 1 \text{ and } c_2 = -2 \text{ (1pt)}$$

c. **2pt** Find the maximum value of  $y(t)$ .

$$\mathbf{ANS.} \quad R = \sqrt{c_1^2 + c_2^2} = \sqrt{5} \text{ (2pt)}$$

d. **2pt** If a periodic external force equal to  $3 \cos \omega t$  Newtons is applied, then for what positive value of  $\omega$  does resonance occur?

**ANS.**  $\omega = \text{natural frequency} = 2$  (2pt)

3. a. **4pts** For a spring-mass system with mass equal to 1 kg, spring constant equal to 25 Newton-sec/meter, which damping constant  $\gamma$  causes critical damping?

**ANS.** Critical damping =  $\sqrt{4mk} = \sqrt{(4)(1)(25)} = 10$

- b. **3pts** If the damping constant  $\gamma$  in the above system is set to 2 Newton-sec/meter, then what can be said about the number of times does the object pass through its equilibrium position?

**ANS.** Since 2 is less than critical damping, infinitely many times.

- c. **4pts** If the damping constant  $\gamma$  in the above system is set to 8 Newton-sec/meter, then what is the interval of time between the second time the object returns to its equilibrium position and the third time it returns to its equilibrium position?

**ANS.**  $y'' + 8y' + 25y = 0$  has characteristic polynomial  $r^2 + 8r + 25$  which has roots  $r = -4 \pm 3i$ . (2pt)

The object returns to equilibrium when  $c_1 \cos 3t + c_2 \sin 3t$  is zero. (1pt)

This happens at intervals of constant length  $\pi/3$ . (1pt)

4. **a. 2pts** What is the definition of the Laplace transform  $\mathcal{L}\{e^{3t}\}$ ?

**ANS.**  $\mathcal{L}\{e^{3t}\} = \int_0^\infty e^{-st} e^{3t} dt$  (2pt)

No credit for any errors.

**b. 4pts** Use the answer to Part **a** to calculate  $\mathcal{L}\{e^{3t}\}$ . (Be sure to explain why this exists only when  $s > 3$ ).

**ANS.**  $\int_0^\infty e^{-st} e^{3t} dt = \int_0^\infty e^{-(s-3)t} dt$  (1pt)

$$\int_0^\infty e^{-(s-3)t} dt = \lim_{A \rightarrow \infty} \frac{-1}{s-3} (e^{-(s-3)A} - 1) \quad (2pt)$$

The limit on the right hand side is  $\frac{-1}{(s-3)}$  whenever  $-(s-3)$  is negative, or equivalently, when  $s > 3$ . (1pt)

**c. 2pts** Suppose that the Laplace transform of  $y$  is  $Y$ . If  $y(0) = 2$  and  $y'(0) = -3$ , then find the Laplace transform of  $y''$ .

**ANS.**  $\mathcal{L}\{y'\} = sY - 2$  (1pt)

$\mathcal{L}\{y''\} = s(sY - 2) - (-3) = s^2Y - 2s + 3$  (1pt)

**d. 3pts** Find the function  $f(t)$  whose Laplace transform is equal to  $\frac{s}{s^2 + 2s + 5}$

**ANS.**  $\frac{s}{s^2 + 2s + 5} = \frac{s}{(s+1)^2 + 2^2}$  (1pt)

$$\frac{s}{s^2 + 2s + 5} = \frac{s+1}{(s+1)^2 + 2^2} - \frac{1}{(s+1)^2 + 2^2} \quad (1pt)$$

$= \mathcal{L}\{e^{-t}(\cos(2t) - (1/2)\sin(2t))\}$  (1pt)

5. a. 5pt Find  $f(t)$  so that  $\mathcal{L}\{f(t)\} = \frac{e^{-3s}}{(s-1)(s+3)}$

ANS.

$$\frac{1}{(s-1)(s+3)} = \frac{1/4}{s-1} - \frac{1/4}{s+3} \quad (2\text{pt})$$

$$\frac{1/4}{s-1} - \frac{1/4}{s+3} = \mathcal{L}\{u(t)((1/4)e^t) - (1/4)e^{-3t}\} \quad (1\text{pt})$$

$$\frac{e^{-3s}}{(s-1)(s+3)} = \mathcal{L}\{u(t-3)((1/4)e^{(t-3)} - (1/4)e^{-3(t-3)})\} \quad (2\text{pt})$$

b. 6pt Assume that acceleration due to gravity  $g$  is equal to 10 meter/sec<sup>2</sup>. An object with mass 2 kg stretches a spring 4 m to equilibrium. At time  $t = 0$  it is released 2 meters below its equilibrium position with an upward velocity of 3 meters/sec. At time  $t = 6$  it is struck with a hammer and as a result its momentum is **decreased** by 7 kg-meters/sec at that moment in time. At time  $t = 8$  a constant external force of 9 Newtons is added and at  $t = 10$  it is removed. Write down a differential equation with initial conditions for the displacement  $y(t)$  of the object below its equilibrium position. **DO NOT SOLVE THIS EQUATION**

ANS.  $2y'' + 5y = -7\delta(t-6) + 9(u(t-8) - u(t-10)) \quad y(0) = 2, \quad y'(0) = -3$

(1pt) for the lhs of the ODE.

(2pt) for each of the two terms on the rhs of the ODE.

(1pt) for the initial conditions.

**6. a. 3pt** Consider the function

$$f(t) = \begin{cases} t, & \text{if } t < 2 \\ 2, & \text{if } 2 \leq t \end{cases}$$

Sketch a graph of this function and find a formula for  $f(t)$  in terms of unit step functions  $u(t - c)$ , for appropriate values of  $c$ . (Note that  $u(t - c)$  and  $u_c(t)$  denote the same function.)

**ANS.**  $f(t) = t((u(t) - u(t - 2)) + 2u(t - 2))$

(1pt) for the graph of  $f(t)$

(1pt) for each of the two terms in the above expression for  $f(t)$ .

**b. 4pt** Determine the Laplace transform of  $f(t)$  in Part **a**

**ANS.** Note that  $f(t) = tu(t) - (t - 2)u(t - 2)$  (1pt)

$$\mathcal{L}\{tu(t)\} = 1/s^2 \text{ (1pt)}$$

$$\mathcal{L}\{(t - 2)u(t - 2)\} = e^{-2s}/s^2 \text{ (2pt)}$$

**c. 4pt** Find the Laplace transform of  $u(t - \pi) \sin(t)$ .

**ANS.** Note that  $\cos(t - \pi) = \sin(t)$  (2pt)

$$\mathcal{L}\{u(t - \pi) \cos(t - \pi)\} = e^{-\pi s} \frac{s}{s^2 + 1} \text{ (2pt)}$$

7. 11pt Solve the following IVP:

$$y' + 3y = \delta(t - 1) + u(t - 2) \quad y(0) = -4$$

ANS.

Take the Laplace transform of both sides:  $sY + 4 + 3Y = e^{-s} + \frac{e^{-2s}}{s}$

(1pt) for the lhs

(1pt) for Laplace of delta

(1pt) for Laplace of unit step fcn.

Hence, solving for  $Y$   $Y = \frac{-4}{s+3} + e^{-s} \frac{1}{s+3} + e^{-2s} \frac{1}{(s+3)s}$

(1pt) for solving for  $Y$

$$\frac{1}{(s+3)s} = \frac{1/3}{s} - \frac{1/3}{s+3} \quad (1\text{pt})$$

Therefore,

$$y(t) = -4e^{-3t} + u(t-1)e^{-3(t-1)} + \frac{1}{3} \left(1 - e^{-3(t-2)}\right) u(t-2)$$

(1pt) for the first term in  $y(t)$

(2pt) for the second term in  $y(t)$

(3pt) for the third term in  $y(t)$

8. **a. 7pt** Find the general solution of  $\mathbf{x}' = A\mathbf{x}$  with  $A = \begin{pmatrix} 1 & -2 \\ 2 & 1 \end{pmatrix}$ . (Note: the solution should be real.)

**ANS.** The characteristic polynomial is  $(1 - r)(1 - r) + 4$ .

The complex eigenvalues are  $1 \pm 2i$ . (2pt)

Then  $A - (1 - 2i)I = \begin{pmatrix} 2i & -2 \\ 2 & 2i \end{pmatrix}$  and hence the corresponding eigenvector is  $\begin{pmatrix} 2 \\ 2i \end{pmatrix}$   
or more simply  $\begin{pmatrix} 1 \\ i \end{pmatrix}$ . (2pt)

A complex solution is

$$e^t e^{2it} \begin{pmatrix} 1 \\ i \end{pmatrix} = e^t (\cos 2t + i \sin 2t) \begin{pmatrix} 1 \\ i \end{pmatrix}$$

(1pt)

We obtain real solutions by taking the real and imaginary parts of the above:

$$\mathbf{x}_1 = e^t \begin{pmatrix} \cos 2t \\ -\sin 2t \end{pmatrix} \quad \mathbf{x}_2 = e^t \begin{pmatrix} \sin 2t \\ \cos 2t \end{pmatrix}$$

(2pt)

- b. 2pt** Sketch a phase portrait for the system given in Part a.

**ANS.** The phase portrait is an expanding spiral. (1pt)

To get its orientation check  $A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ , ie, oriented counter-clockwise. (1pt)

- c. 1pt** Which of the six names for the critical points fits the critical point of this system.

**ANS.** Spiral

- d. 1pt** What is its stability?

**ANS.** Unstable



9. In Parts **a** and **b** of this Problem do the following:

i. Sketch a phase portrait for this system.

ii. State the name associated with the critical point at  $(0, 0)$  and state whether it is stable, asymptotically stable or unstable?

**a. 4pt** The homogeneous linear system  $\mathbf{x}' = A\mathbf{x}$  whose general solution is:

$$\mathbf{x} = c_1 e^{-3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

**ANS.**

Total of eight trajectories required.

(1pt) for the “basic four” corresponding to the eigenvectors.

(1pt) for the remaining ones

Node (1pt)

Asymptotically stable (1pt)

**b. 4pt** The homogeneous linear system  $\mathbf{x}' = A\mathbf{x}$  whose general solution is:

$$\mathbf{x} = c_1 e^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

Total of eight trajectories required.

(1pt) for the “basic four” corresponding to the eigenvectors.

(1pt) for the remaining ones

Node (1pt)

Unstable saddle (1pt)

In parts **c.** and **d.** of this Problem do the following:

determine the stability and the name associated with the critical point of the system at the origin.

**c. 2pt**  $\mathbf{x}' = A\mathbf{x}$  with  $A = \begin{pmatrix} 3 & 1 \\ 0 & 3 \end{pmatrix}$ .

**ANS.** Improper node.(1pt)

Unstable (1pt)

**d. 2pt**  $\mathbf{x}' = A\mathbf{x}$  with  $A = \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix}$ .

**ANS.** Proper node.(1pt)

Unstable (1pt)